

Estimation of hydraulic parameters by using VES sounding and neural network techniques in the semi-arid Khanasser valley region, Syria

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Abstract: An alternative approach based on using Vertical Electrical Sounding (VES) measurements and Artificial Neural Network (ANN) technique is newly proposed for computing the hydraulic conductivity K and the transmissivity T of an aquifer. VES measurements in the locations, where available water samples exist are required in such an approach, in order to train a neural network with fitting capability to evaluate both the hydraulic conductivity and transmissivity. The hydraulic conductivity and transmissivity are thereafter extrapolated by the use of trained neural network, even in the VES points where no water samples exist. This approach is practiced and tested in the Khanasser valley, Northern Syria, where the hydraulic conductivity and the transmissivity of the Quaternary aquifer is computed. We find an acceptable agreement between the hydraulic conductivity values obtained by the new approach and those obtained by the pumping test, which range between 0.864 and 8.64 m/day.

Key words: Hydraulic conductivity, Transmissivity, VES Sounding, Khanasser Valley, Syria

1. Introduction

The aquifer behaviour during the different stages of water extraction is predicted by the groundwater modelling by the use of the hydraulic conductivity parameter, considered as the most important in hydrogeology. The pumping tests technique is traditionally applied to estimate the hydraulic conductivity, but this technique is affected being expensive and yields to low sparse resolution maps.

Geophysical methods are largely used to develop alternative approaches, aimed at estimating the hydraulic parameter, where specific relationships

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between hydro-geological and geophysical parameters are provided (*Heigold et al., 1979; Frohlich, 1994; Frohlich et al., 1996; Yadav and Abolfazli, 1998; Salem, 1999; De Lima and Niwas, 2000; Niwas and De Lima, 2003; Dhakate and Singh, 2005; Lesmes and Friedman, 2005; Asfahani, 2007a,b,c; Asfahani, 2010a,b; Arétouyap et al., 2015; Arétouyap et al., 2019a; Arétouyap et al., 2019b*).

We propose in this paper a new practical technique based on the application of vertical electrical sounding (VES) and ANN techniques to estimate the aquifer hydraulic conductivity and transmissivity.

The application of VES technique offers different advantages in comparing with the traditional pumping tests technique. Accordingly, we do not need a ground perforation, where faster information regarding the hydraulic conductivity distribution is obtained with high resolution maps, by the use of dense VES sounding points.

The new proposed neural networks approach takes into consideration only the groundwater salinity, for characterizing the Quaternary aquifer hydraulic conductivity and transmissivity in the semi-arid Khanasser valley region, Northern Syria, Fig. 1.

The ability of ANN as universal function approximator is used in this paper to provide a data-driven approximation of the relation between hydraulic conductivity and hydraulic transmissivity and the saturated aquifer resistivity and the saturated thickness of the Quaternary aquifer. This requires the hydraulic conductivity and transmissivity measurements using pumping tests, which are expensive and complex to operate. Four pumping tests are only available in this work (*Asfahani, 2016*), which are not sufficient to train ANN. The recent computed values of hydraulic conductivity and transmissivity based on VES measurements (*Asfahani, 2016*), and the measured available four pumping test values are therefore used to train ANN.

Geophysical researches have been practiced in the Khanasser Valley through an international research program, directed by three scientific organizations; Bonne University, Germany, International Center for Agriculture Research in the Dry Areas (ICARDA), and Syrian Atomic Energy Commission (*Schweers et al., 2002*). The specific problems related to the marginal dry-land environments were solved by this research program.

Livelihoods, the diversity and dynamics of the natural resources, poverty and the relative easy accessibility made Khanasser as a prime candidate.

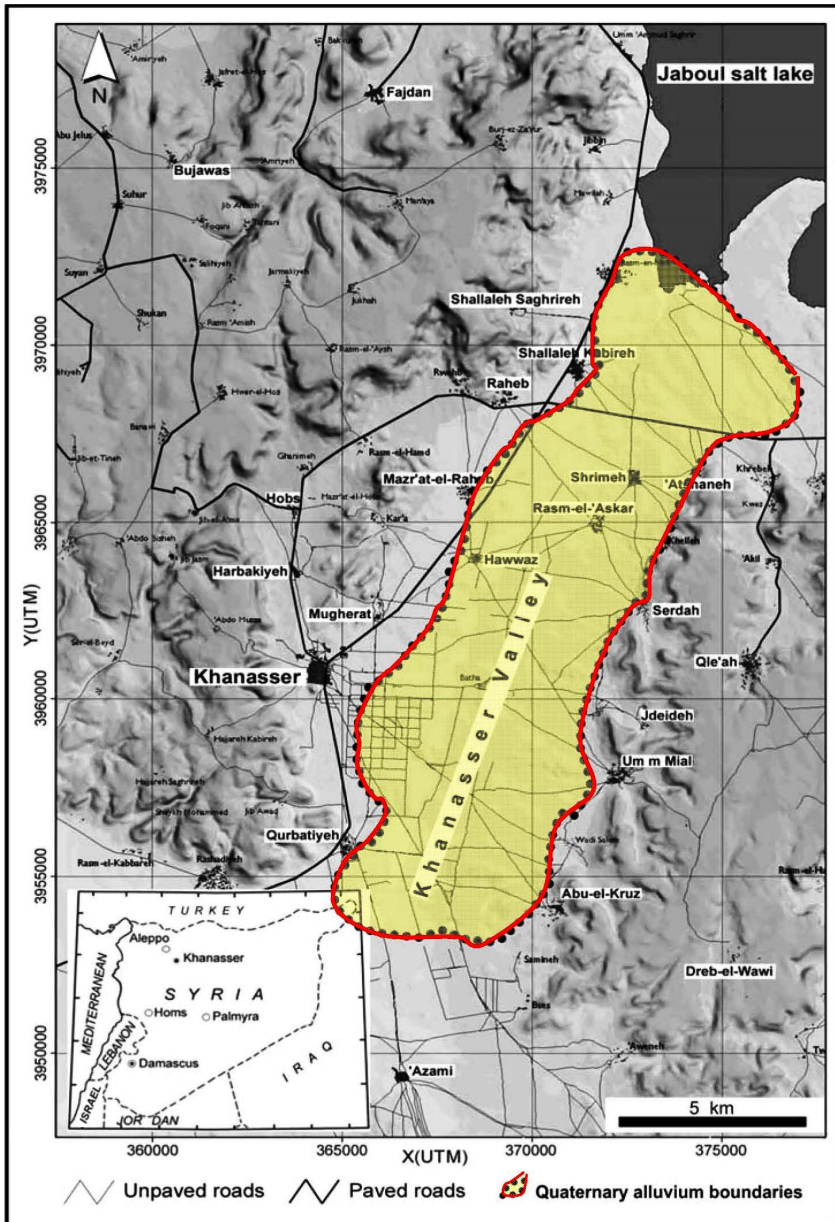


Fig. 1. Location of Khanasser valley, Northern Syria.

The rainfall in the Khanasser region is low and unpredictable, while the natural resources are quite poor and prone to degradation. Annual rainfall ranges between 200 and 250 mm/year, but the annual rainfall extremes between 1957 and 2001 were 93 and 393 mm (*Soumi, 1991*).

2. Hydrogeology of the Khanasser Valley

Khanasser Valley study area lies between two hill ranges; the Jabal Shbeith in the east and the Jabal Al Hoss in the west, and is located approximately 70 km southeast of Aleppo City. The drainage of the northern part of the valley is towards the Jaboul salt lake, while the drainage of the southern part is towards the Adami depression in the south, (Figs. 1 and 2). Fig. 3 shows a geological cross-section along the transverse geoelectrical profile TP5.

The groundwater extraction in the Khanasser Valley is achieved through three aquifers. The deepest one related to upper Cretaceous is at 400 m below ground level. The second one is the Paleocene-Lower Eocene limestone aquifer of a low productivity (*ACSAD, 1984*), its average hydraulic conductivity (k) is 0.0054 m/day as referred from the pumping test (*Schweers et al., 2002*). A hydraulic conductivity ranging between 0.008 m/day and 0.5 m/day for the Paleogene formation was already revealed by *Lengiprovodkhoz Institute (1987)*.

In the central part of Khanasser valley, the paleogene strata are not very thick; about 50 m of lower Eocene and Paleocene are found above the Maestrichtian. The most transmissive third aquifer in the region is the Quaternary water bearing formations, that are situated near the surface, and covered by some of 10 m of alluvial and proluvial soil. The direct recharge from rainwater as well as infiltrating runoff and subsurface flow from the slopes of Jabal Al Hoss and Jabal Shbeith are the main source for this aquifer. The substantial increase in groundwater withdrawal from the upper, unconfined aquifer system observed during the last two decades is due to the rapid development of motorized irrigation wells. Khanasser valley might be affected by salt water intrusion from the Jaboul salt lake as indicated by the analysis and the groundwater monitoring, where considerable changes in quality and water level are observed since 1998 (*Hoogeveen and Zobisch, 1999*).

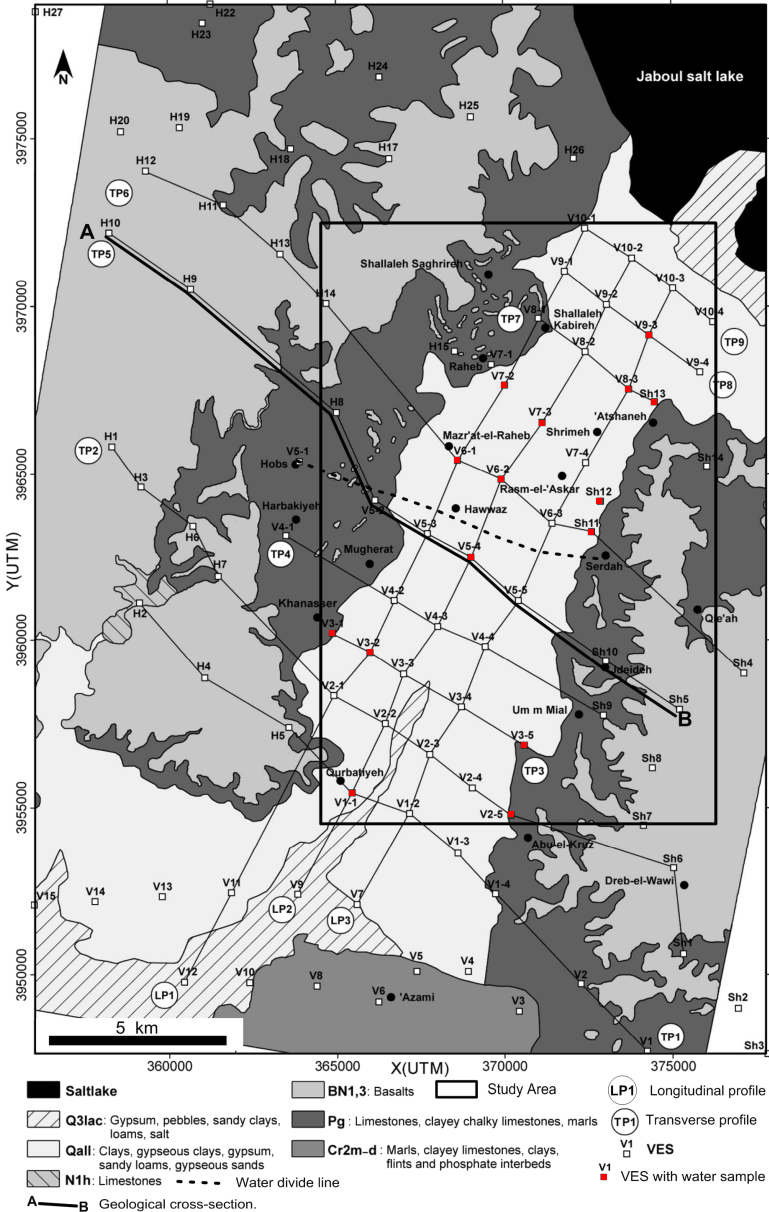


Fig. 2. Geological map of Khanasser valley and its surroundings (after Ponikarov and Mikhailov, 1964), with the locations of VES soundings (Asfahani, 2016).

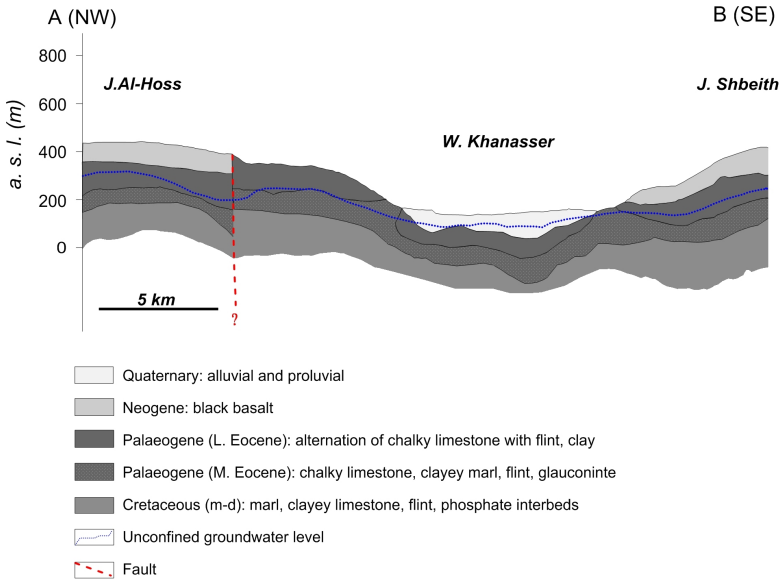


Fig. 3. Geological cross-section along the transverse geoelectrical profile TP5 (Asfahani, 2013).

3. VES measurements and interpretation

Schlumberger configuration was used during the Khanasser Valley research program to carry out ninety-six vertical electrical resistivity soundings VES, where their locations are shown on Fig. 2 (Asfahani, 2010a, and Asfahani, 2007a).

The AB/2 current electrode spacing was ranged for all the VES soundings between a minimum of 3 m and a maximum of 500 m.

The two current electrodes (A and B) are symmetrically expanded about the centre of the spread, while the potential electrodes (M and N) remain fixed. The apparent resistivity (ρ_a) for a given position of the current and potential electrodes is written by the following equation:

$$\rho_a = \frac{2\pi}{\frac{1}{AM} - \frac{1}{BM} - \frac{1}{AN} + \frac{1}{BN}} \frac{\Delta V}{I},$$

where I is the current introduced into the earth, ΔV is the potential dif-

ference between the potential electrodes, and AM , BN , AN and BN are interelectrode spacing.

Curve matching technique with the use of master curves is practiced to interpret the field resistivity curves (Orellana and Mooney, 1966), and to get the initial determination of resistivities and thicknesses of corresponding layers (initial approximate model). An inverse technique program is thereafter used to correctly interpret the initial model parameters, until a goodness of fit between the resistivity field curve and the computed regenerated curve is obtained (Zohdy, 1989; Zohdy and Bisdorf, 1989). The one-dimensional medium 1D is assumed in the studied Khanasser region.

Fig. 4 shows a field VES example at the point V10-4 and its 1D interpretative model.

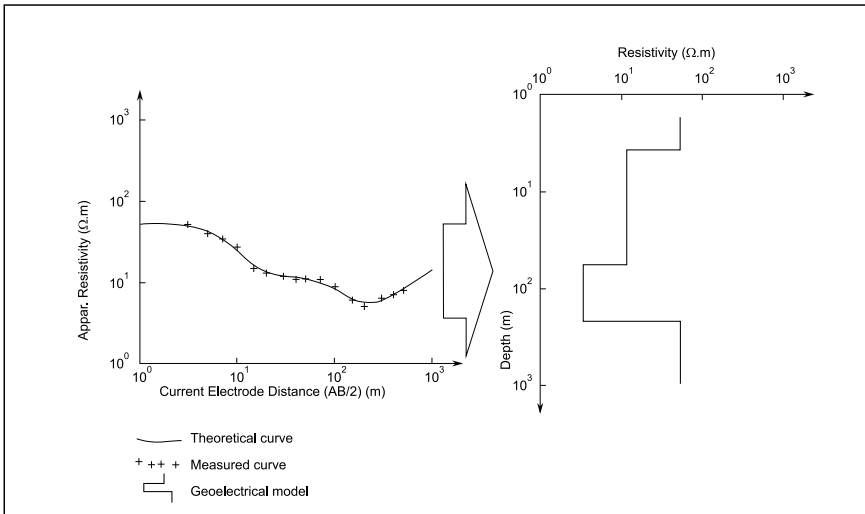


Fig. 4. Field VES example and its 1D interpretation at the location V10-4.

The 1D quantitative interpretations of these ninety six VES, distributed on the twelve profiles, (both transverse and longitudinal) enabled (Asfahani, 2007a) identification of both the geometry of the Khanasser Valley and the geo-electrical characteristics of Quaternary, Paleogene and Maistrehtian deposits. Fig. 5 presents the geo-electrical interpretative section established for the VES distribution along the TP5 transverse profile (TP5 corresponds to the geological section shown in Figs. 2 and 3), which shows the resistivity

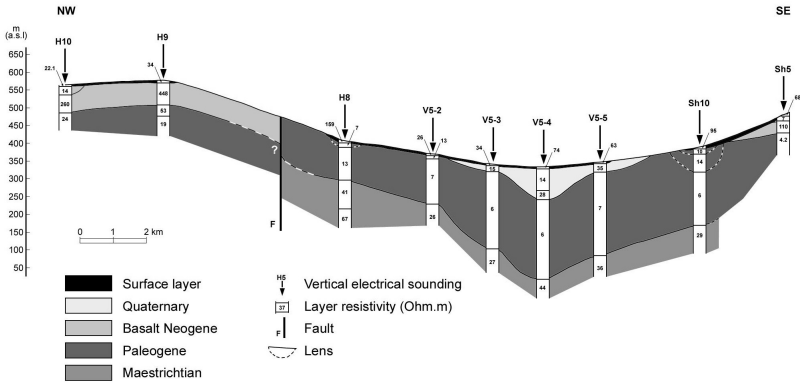


Fig. 5. Geoelectrical interpretation along TP5 (Asfahani, 2013).

and thickness values of the Quaternary and Paleogene aquifers.

Asfahani (2007a) has indicated to the presence of two main geological structures, one in the north and the other in the south of the line joining the towns of Hobs and Sirdah. This observation has been confirmed for all the geoelectrical maps corresponding to different spacings AB/2 (from 3 m to 500 m), revealing that a clear deep tectonic effect is present along this joining line.

4. Artificial Neural Networks

An Artificial Neural Network (ANN), like their biological analogues consists of a number of interconnected processing neurons, which are logically arranged in several layers that interact with each other through weighted connections. ANN can be used as mathematical tools that have found several applications in a wide range of research areas (Basheer and Hajmeer, 2000). Moreover, it has been proven theoretically that multilayer feedforward networks called Multi Layer perceptron (MLP) are universal approximators (Hornik et al., 1989; Hornik, 1991).

A MLP consists of an input layer, an output layer and several hidden layers. Node in a MLP network is called a neuron as shown in Fig. 6. It includes a summer and a nonlinear activation function g . The number of neurons in each layer and the number of layers in the network depend on the nature of the problem. The number of hidden nodes is a critical parameter

of any MLP. Too many nodes may cause over fitting the data, thus resulting in poor generalization on data not used for training. On the other hand, too few hidden nodes will cause under fitting of the model, which will therefore be insufficiently accurate. Most of the mathematics behind the connections and processing within the nodes are in fact linear combinations (*Basheer and Hajmeer, 2000*).

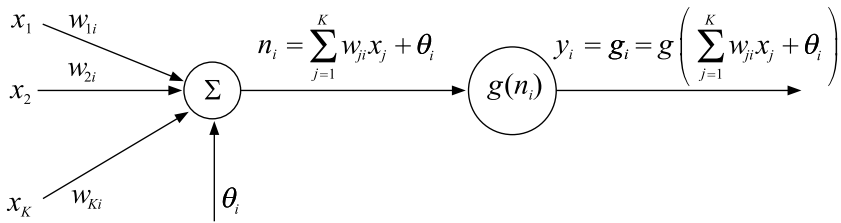


Fig. 6. Single neuron model.

The inputs x_k , $k = 1, \dots, K$ to the neuron are multiplied by scalar weights w_{ki} and summed up together with the constant bias term θ_i . The scalar weights determine the nature and strength of the influence between the interconnected neurons. Each neuron is connected to all the neurons in the next layer. The resulting η_i is the input to the activation function g . The activation function was originally chosen to be a relay function, but for mathematical convenience a hyperbolic tangent (tanh) or a sigmoid function are most commonly used.

The output of node i becomes:

$$y_i = g \left(\sum_{j=1}^K w_{ji} x_j + \theta_i \right). \tag{1}$$

A MLP network is formed by connecting of several nodes in parallel and series, where a typical network is shown in Fig. 7.

The output y_i of the network becomes:

$$y_i = g \left(\sum_{j=1}^3 w_{ji}^2 g \left(n_j^1 \right) + \theta_j^2 \right) = g \left(\sum_{j=1}^3 w_{ji}^2 g \left(\sum_{k=1}^K w_{ji}^1 x_k + \theta_j^1 \right) + \theta_j^2 \right). \tag{2}$$

From (2) we can conclude that a MLP network is a nonlinear parameterized map from input space \mathbf{X} to output space \mathbf{Y} . The parameters are the

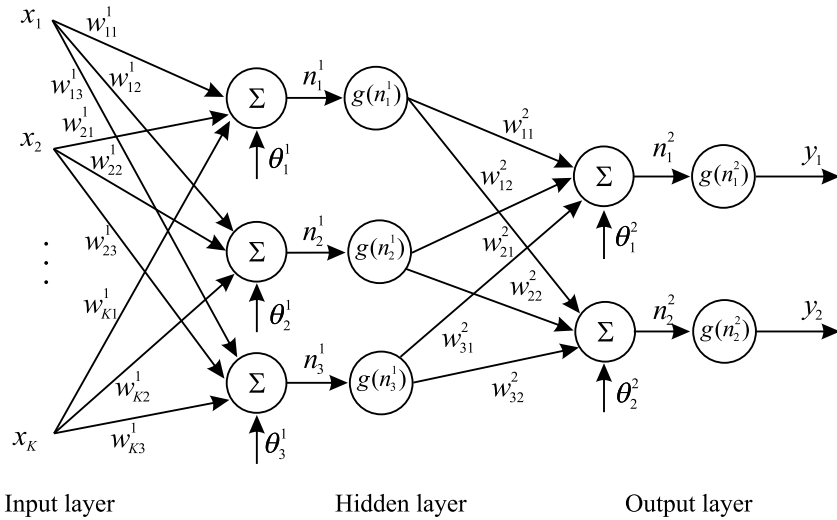


Fig. 7. A network with one hidden layer.

weights w_{ij}^k and the biases θ_j^k . Activation functions g are assumed to be the same in each layer and known in advance. The same activation function g in the figure is used in all layers.

Given input-output data $(x_i, y_i), i = 1, 2, \dots, N$ finding the best MLP network is formulated as a data fitting problem. The parameters to be determined are (w_{ij}^k, θ_j^k) .

The procedure functions as follows; the designer has to fix the structure of the MLP network architecture and the number of hidden layers and neurons (nodes) in each layer. The activation functions for each layer are selected and assumed to be known at this stage. The weights and biases are the unknown parameters to be estimated.

Several algorithms exist for determining the network parameters. The algorithms in neural network literature are called *learning* or *teaching* algorithms, and belong to *parameter estimation* algorithms in the system identification.

The most well-known are back-propagation and Levenberg-Marquardt algorithms. Back-propagation is a gradient based algorithm, which has many variants. Levenberg-Marquardt is usually more efficient, but needs more computer memory. We will concentrate herein only on using the teaching

algorithms. The procedure of teaching algorithms for multilayer perceptron networks is summarized as follows:

1. At first the structure of the network is defined. Activation functions are chosen in the network, where the network parameters of weights and biases are initialized.
2. The parameters associated with the training algorithm as error goal, maximum number of epochs (iterations), etc, are defined.
3. The training algorithm is called.

After determining the neural network, the result is first tested by simulating the output of the neural network with the measured input data. This is compared with the measured outputs. Final validation must be carried out with independent data.

5. Application to hydraulic parameters estimation

As mentioned in section 2, ANN act as universal function approximators. This makes them useful in modelling problems in which the relation between dependent and independent variables is poorly understood. The ability of ANN is used in this paper to provide a data-driven approximation of the relation between hydraulic conductivity K and the saturated aquifer resistivity ρ_{rock} and the saturated thickness of the Quaternary aquifer h and between transmissivity T and ρ_{rock} and h as illustrated in Fig. 8.

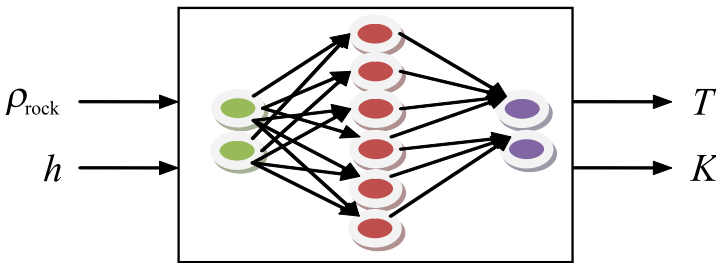


Fig. 8. Black box model of ANN used in this work.

Applying ANN requires the measurement of hydraulic conductivity and transmissivity using pumping tests which are expensive and complex to operate. Four pumping tests are only available in this work (Asfahani, 2016),

which are not sufficient to train ANN. The computed values of hydraulic conductivity and transmissivity based on VES measurements, recently obtained by *Asfahani (2016)* and additional four available pumping test measured values are therefore used to train ANN.

The proposed approach described herewith based on Artificial Neural Network is established as follows:

1. Firstly, carry out VES measurements in the locations where water samples related to Quaternary aquifer are available to evaluate the water resistivity ρ_w . Fifteen VES measurements have been measured and identified as close to the water sample locations. Those 15 VES soundings have been interpreted quantitatively, where the resulting resistivity and thickness of the saturated Quaternary aquifer (ρ_{rock} and h) are shown in Table 1 (*Asfahani, 2016*).
2. Determine the formation factor F used in Archie's law 1942 (*Archie, 1942*).
3. Compute the corresponding hydraulic conductivity K by using Salem's formula 2001 (*Salem, 2001; Asfahani, 2016*).
4. Compute the aquifer transmissivity T by knowing of the average \bar{K} of hydraulic conductivity and h .
5. Train an artificial neural network using the data computed in step 2, 3, 4 and shown in Table 1.
6. Secondly, carry out VES measurements in the locations where no water samples exist.
7. Use the neural network trained in step 5 to extrapolate the hydraulic conductivity K and transmissivity T in VES locations, even where no water samples exist.

The formation factor F used in Archie's law in its general form is computed as the ratio of ρ_{rock} and ρ_w as follows:

$$F = \frac{\rho_{rock}}{\rho_w}, \tag{3}$$

where ρ_{rock} is the saturated aquifer resistivity estimated from the quantitative interpretation of (VES), and ρ_w is the pore fluid resistivity. Water resistivity ρ_w is obtained through converting water conductivity.

Salem's formula 2001 which takes only the groundwater salinity into consideration relates hydraulic conductivity K with formation factor F obtained by using VES method. It is applied to obtain the hydraulic conductivity K as follows:

$$K = 0.66528 * F^{2.09} . \quad (4)$$

The following equation is used to compute the transmissivity T for the interpreted fifteen VES as follows:

$$T = \bar{K} * h , \quad (5)$$

where \bar{K} is the average of hydraulic conductivity of the available fifteen water samples shown in Table 1.

6. Results and discussion

MATLAB Neural Network Toolbox is used to create and train ANN with fitting capability to evaluate the hydraulic conductivity and transmissivity (MATLAB, 2009). The MATLAB commands used in the procedure are *newff*, *train* and *sim*. The *train* procedure requires measured input and measured outputs data. The measured inputs in this work are the resulting thickness and resistivity of the saturated Quaternary aquifer (ρ_{rock} and h) shown in Table 1, while the measured outputs are the computed values of K and T in the 15 VES locations, where water samples related to Quaternary aquifer are available.

Four available measured values of K using pumping test are used instead of the calculated K of VES ones at VES locations of V1-1 (at the locations of Qurbatieh), V3-1 (Khanasser), V5-4 (Batha), and V6-2 (Rasm Askar), where the hydraulic conductivity were 1.55 m/day, 4.4 m/day, 6.56 m/day, and 54.4 m/day respectively (Schweers *et al.*, 2002).

The training error of the ANN is shown in Fig. 9. The goal error is reached after 600 training epoch and the performance is quite acceptable.

The results shown in Table 1 are used for applying the developed approach, and for training an ANN. The average aquifer water resistivity ρ_w of the 15 water samplings is 3.35 Ω .m. It is rather used for computing the formation factor F expressed in Eq. (3).

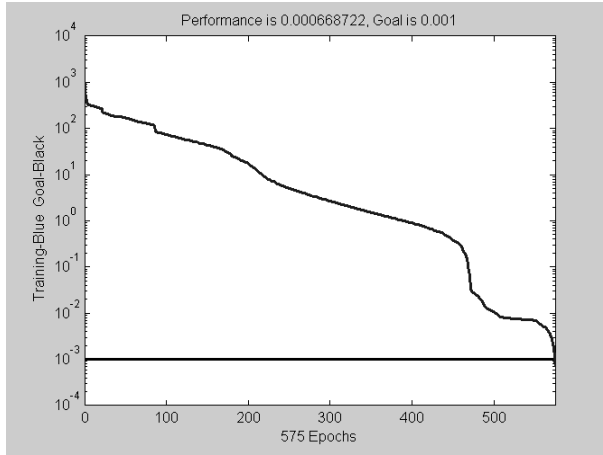


Fig. 9. Training error convergence.

Figs. 10a and 10b show the variations of both resistivity ρ and thickness h of the Quaternary aquifer for the 34 VES locations (15 VES with water samples and 19 VES without water samples) in the Khanasser valley.

Table 1. Data used to train ANN.

Location	ρ_w ($\Omega.m$)	ρ_{rock} ($\Omega.m$)	h (m)	K (m/day)	K^* (m/day)	T (m^2/day)
V6-1	3.03	8.5	12	4.65		165.6
V9-3	1.3	11	22.5	7.98		310.5
V2-5	2.16	9.6	23.8	6		328.44
V1-1	1.79	6.5	31.4	2.65	1.55	433.32
Sh11	2.506	30	31.9			440.22
Sh12	7.44	15.5	25	16.3		345
Sh13	4.52	9	10	5.25		138
V8-3	3.47	17	11.5	19.82		158.7
V3-1	6.85	10	7.7	6.54	4.4	106.26
V3-2	6.02	15	25	15		345
V7-2	4.33	16	6	17.5		82.8
V7-3	3.03	16	5.7	17.5		78.66
V3-5	1.67	19	12.9	25		178.02
V5-4	1.2	14	59	13	6.56	814.2
V6-2	1	23	17.2	37	54.4	237.36

K^* is the pumping test value.

The hydraulic conductivity estimated according to Salem formula varies between a minimum of 2.65 m/day at VES location V1-1 and a maximum of 37 m/day at VES location V6-2 with an average of 13.8 m/day and a standard deviation of 9.4 m/day. The transmissivity is evaluated by using Eq. (5), and by using an average \bar{K} of 13.8 m/day. It varies between a minimum of 79 m²/day at the VES location V7-3 and a maximum of 814 m²/day at the VES location V5-4 with an average of 277 m²/day.

The application of the resulting trained ANN allows obtaining K and T in nineteen VES points, where no water samples exist. This is done to characterize as a first approximation the Quaternary aquifer in the Khanasser valley (Table 2). The conductivity and transmissivity values shown in Table 2 are directly obtained by using the trained ANN. E_K and E_T in the Table 2 are the absolute difference between K and T values computed using ANN and those computed using the approach proposed in (Asfahani, 2016). E_K

Table 2. Calculated hydraulic conductivity K and transmissivity T by ANN, in VES locations where no water samples exist.

Location	h (m)	ρ_{rock} ($\Omega \cdot \text{m}$)	K (m/day)	T (m ² /day)	E_K	E_T
V10-4	53	12	7.43	396.88	0.84	41.66
V10-3	18	7	10.67	207.74	0.03	15.05
V10-1	34	10	8.65	312.68	0.05	16.83
V10-2	40	15	10.52	386.57	0	34.61
V9-1	21	15	13.08	276.26	0.43	7.54
V9-2	50	4.3	5.22	207.60	0.51	27.99
V9-4	21	9	8.62	173.93	2.00	49.13
V8-2	16.7	11	13.76	242.24	0.56	21.74
V6-3	35	17	13.03	397.05	1.07	21.72
V5-3	15	15	17.19	248.28	1.17	7.87
V5-5	14	36	28.31	383.68	1.54	8.77
V4-3	4.5	22	40.08	180.05	0.16	0.38
V3-3	19	15	15.12	242.29	0.95	27.04
V3-4	11.8	26	25.05	253.33	1.34	26.51
V2-1	15	43	28.76	426.29	0.76	16.59
V2-2	9	6.6	17.16	141.53	0.68	19.05
V2-3	8.5	8	18.80	147.33	0.58	17.40
V2-4	14	11.5	12.75	240.41	2.21	30.85
V1-2	58	10	6.92	413.83	0.17	2.29

varies between a minimum of 0, and a maximum of 2.21 m/day, with an average of 0.97 m/day and a standard deviation of 0.64 m/day. E_T varies between a minimum of 0.38 m²/day and a maximum of 49.13 m²/day, with an average of 20.68 m²/day and a standard deviation of 12.87 m²/day.

The hydraulic conductivity values K for the 19 VES points vary between a minimum of 5.22 m/day at VES location V9-2, and a maximum of 40.08 m/day at VES location V4-3, with an average of 15.85 m/day and a standard deviation of 9.00 m/day.

The transmissivity values for the 19 VES vary between a minimum of 141.53 m²/day at VES location V2-2, and a maximum of 426 m²/day at VES location V2-1, with an average of 277.79 m²/day and a standard deviation of 95.56 m²/day. Table 3 shows the statistical results of K and T for the 19 VES points obtained by using ANN technique.

Table 3. statistical parameters using 19 VES points with no water samples.

	h (m)	ρ_{rock} ($\Omega.m$)	K (m/day)	T (m ² /day)	E_K	E_T
Min	4.5	4.3	5.22	141.53	0	0.38
Max	59	43	40.08	426.29	2.21	49.13
Average	22	14.8	15.85	277.79	0.79	20.68
SD	15	8.5	9.00	95.56	0.64	12.87

The hydraulic conductivity values K for the total of thirty four VES points (15 VES with water samples, and 19 VES with no water samples) vary between a minimum of 1.55 m/day at the VES location V1-1, and a maximum of 54.4 m/day at the VES location V6-2, with an average of 15.24 m/day and a standard deviation of 11 m/day as shown in Fig. 10c.

The transmissivity values for the total of thirty four VES points (15 VES with water samples, and 19 VES with no water samples) vary between a minimum of 78.66 m²/day at the VES location V7-3, and a maximum of 814.2 m²/day at the VES location V5-4, with an average of 277.65 m²/day and a standard deviation of 143.58 m²/day as shown in Fig. 10d.

The established transmissivity map (Fig. 10d) clearly indicates a distinct transmissive structure at the south of Hobs-Sirdah joining line delineated by (Asfahani, 2007a). It is low at the north of this joining line and increases towards the Sabkha.

The geophysical and hydrogeological parameters computed for the Qua-

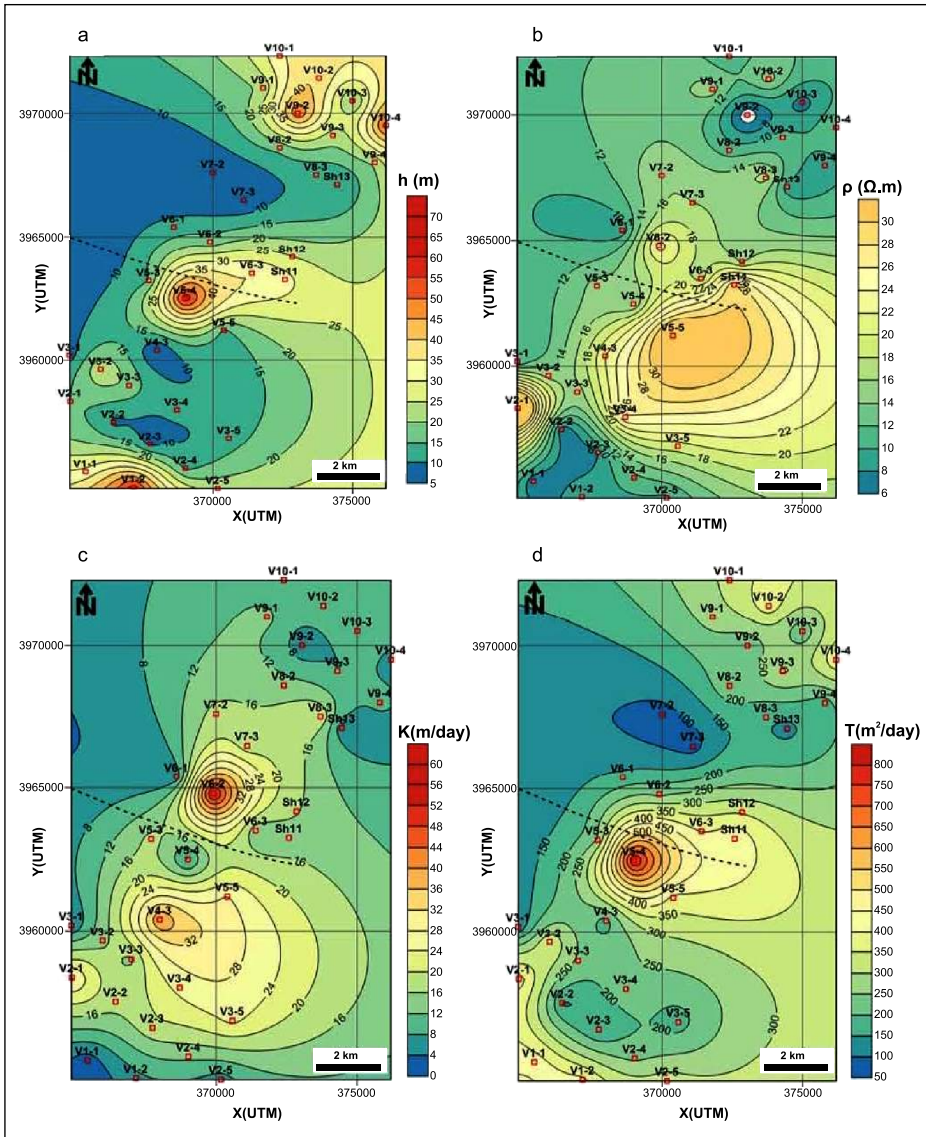


Fig. 10. a: Thickness of Quaternary aquifer h in 34 VES locations in the study area, b: Resistivity ρ of Quaternary aquifer in 34 VES locations in the study area, c: Hydraulic conductivity K of Quaternary aquifer in 34 VES locations in the study area, d: Transmissivity T of Quaternary aquifer in 34 VES locations in the study area.

ternary aquifer at the totality of thirty four VES points in the Khanasser valley are summarized in the Table 4.

Table 4. Geophysical and hydrological parameters at 34 VES points for Quaternary aquifer in the Khanasser valley, Syria.

	ρ_{rock} ($\Omega.m$)	h (m)	K (m/day)	T (m^2/day)
Min	4.3	4.5	1.55	78.66
Max	43	59	54	814.2
Average	14.8	22	15.24	277.65
SD	8.5	15	10.97	143.58

The high transmissivity and yields is related directly to the high thickness of alluvial gravels and sands, labelled as rammel aswad of the Quaternary aquifer in the Khanasser valley. The large differences and the drastic change in the productivity of wells is due to sharpen lateral and vertical variations of rammel aswad from place to place even in very short distances.

The transmissivity distribution obtained geophysically by applying the developed ANN approach for characterizing the Quaternary aquifer in the Khanasser valley is in a good agreement with the field hydrogeological observations. This proves the possibility of applying this technique to characterize the aquifer systems in the semi-arid regions worldwide.

7. Conclusion

A new alternative approach based on using both artificial neural network ANN technique and Vertical electrical sounding (VES) techniques is proposed to compute the hydraulic conductivity K and the transmissivity T of an aquifer.

We train a neural network in the VES locations, where available water samples exist to estimate the hydraulic conductivity and transmissivity. This trained neural network is required to extrapolate the hydraulic conductivity and transmissivity in the VES locations without water samples.

According to this ANN approach, the hydraulic conductivity and the transmissivity of the Quaternary aquifer in the Khanasser valley, Northern Syria are computed. We find an acceptable agreement between the hydraulic conductivity values obtained by the ANN approach and the real hydrolog-

ical situation, obtained by the pumping test, which range between 0.864 and 8.64 m/day. The main advantage of ANN approach is the possibility to integrate VES measurements and pumping test, and no intermediate empirical relations are needed. ANN approach can provide a greater accuracy in predicting K and T if more pumping test were available, and it can be easily extended using additional input parameters as soil porosity and density which could potentially further increase the performance. The easy ANN approach is recommended to be extended for treating other hydrogeological problems related to semi-arid regions worldwide.

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